

# Keith Fritz

Robotics Engineer

## EDUCATION

**Texas A&M University**, College Station, TX  
Multidisciplinary Engineering Technology (Mechatronics),  
Minor in Embedded Systems Integration

## WORK EXPERIENCE

### Field Engineer

ARIS Technology – *Chicago, IL* Feb 2024 – September 2024

- Led the design, testing, and implementation of advanced robotic 3D scanning systems, ensuring successful delivery and integration for multiple clients across various industries.
- Managed large-scale system design and electrical work, contributing to the seamless operation and reliability of complex robotic systems.
- Developed proficiency in FANUC robots and Creaform 3D scanning technology, applying these skills to enhance system performance and accuracy.
- Coordinated with cross-functional teams to troubleshoot and resolve technical issues on-site, ensuring optimal system functionality and customer satisfaction.
- Successfully managed the delivery of multimillion-dollar 3D scanning robotic systems for ARIS Technology.

Aug 2021 – Nov 2023

### Robotics Research Engineer / Science Associate II

University of Texas at Austin – *Austin, TX*

- Facilitated ML/AI research for service and social robots, autonomous vehicles, and human-robot interfaces within the Texas Robotics consortium.
- Provided hardware and software expertise for robotic platforms, including manipulators and autonomous systems.
- Managed a state-of-the-art fabrication lab equipped with 3D printing, laser cutting, metalworking machines, and electrical equipment, supporting rapid prototyping and fabrication needs.
- Designed, prototyped, and tested hardware systems for various commercial and custom-built robotics platforms
- Worked extensively with Boston Dynamics Spot, Clearpath Husky, Jackal, Segway RMP220, Kinova Gen3, and Universal Robots UR5.
- Supported the integration of cutting-edge technology into existing robotic platforms, ensuring seamless operation and performance.
- Contributed as a core team member in the development of a magnetic-driven oil tank inspection robot, leading to the formation of Pike Robotics and a pending patent.

## DETAILS

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## SKILLS

- Robotic System Design
- 3D Scanning & Metrology
- Fabrication & Prototyping
- Embedded Systems
- Electrical System Design
- ROS, C++, Python
- Additive Manufacturing
- Project Management
- Human-Robot Interaction

## KEY PROJECTS

### ARIS Large System Delivery

Played a major role in the design, assembly, and delivery of large industrial robotic 3D scanning systems.

### Pike Robotics

Designed subsystems and led developmental testing for patent pending oil tank inspection robot.

### Aquatic Research Drone

Project Manager for a team that designed and created a semi-autonomous water sampling drone.

## REFERENCES

Available upon request.